Informative Features for Model Comparison

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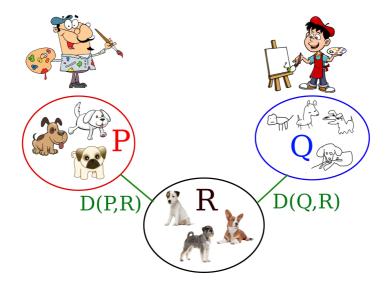






Swiss Data Science Center 29 October 2019

Model Comparison



- Both models *P*, *Q* can be wrong.
- **Goal**: pick the better one.

Outline

- 1 Problem setting
- 2 Motivations for the proposed test
- 3 Hypothesis testing 101
- 4 The Unnormalized Mean Embeddings (UME) statistic (3-sample test)
 - 1 Asymptotic distributions
 - 2 Interpretability
- 5 Experiments
- 6 The Finite Set Stein Discrepancy (FSSD) statistic (2 density models and 1 set of samples)

- \blacksquare P, Q : candidate generative models that can be sampled e.g., GANs.
- R: data generating distribution (unknown).
- Observe $X_n \stackrel{i.i.d.}{\sim} P$, $Y_n \stackrel{i.i.d.}{\sim} Q$, and $Z_n \stackrel{i.i.d.}{\sim} R$ be three sets of samples, each of size n.

 $H_0: P$ and Q equally model R $H_1: Q$ models R better.

Formulate as

 $H_0: D(P, R) - D(Q, R) = 0$ $H_1: D(P, R) - D(Q, R) > 0,$

for some distance D.

Statistic: $\hat{S}_n = \hat{D}(P, R) - \hat{D}(Q, R)$. Large, positive $\implies Q$ is better.

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A common approach: Compare $\hat{D}(P, R)$ and $\hat{D}(Q, R)$ estimated from samples (e.g., FID). If $\hat{D}(Q, R) < \hat{D}(P, R)$, conclude that Q is better than P.

Problems:

- 1 Noisy decision. \widehat{D} is random. ightarrow Statistical testing accounts for this.
- 2 Not interpretable. A scalar \widehat{D} is not informative enough.

 $Q = {
m LSGAN}$ [Mao et al., 2017] $\qquad P = {
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- 1's from Q are better. But 3's from P are better.
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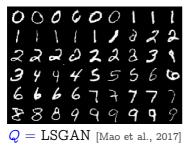
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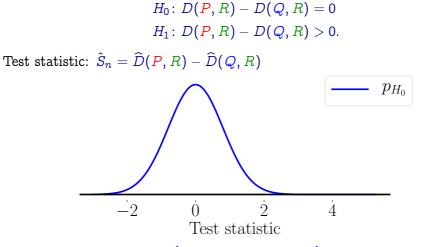


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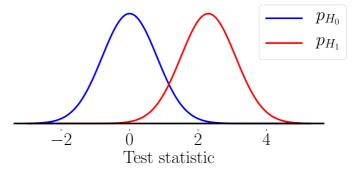
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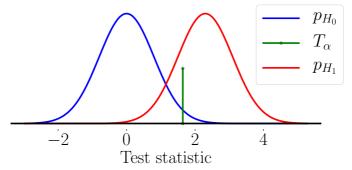
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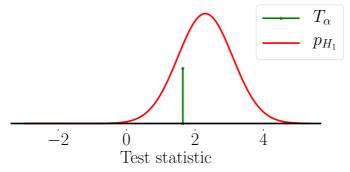
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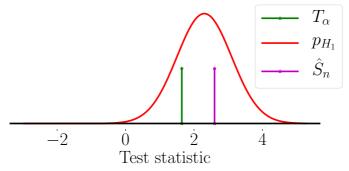
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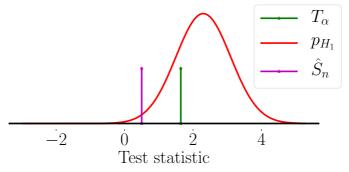
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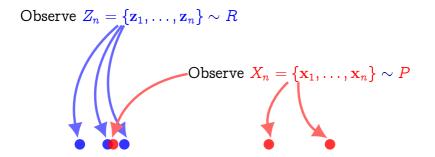
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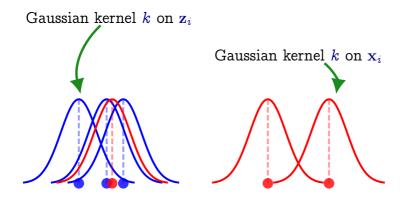
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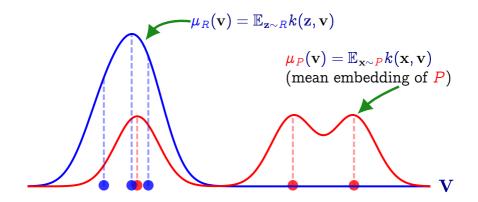


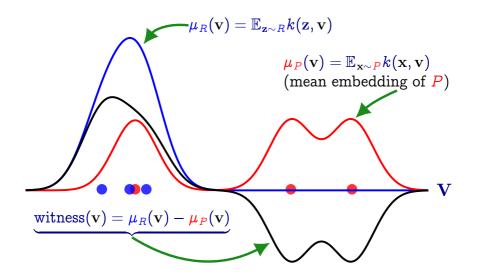
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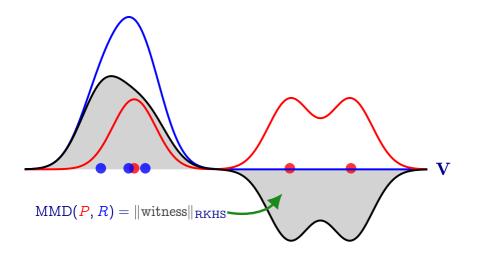
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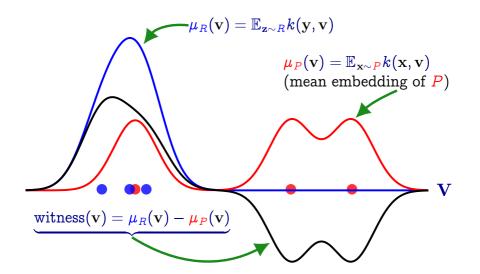




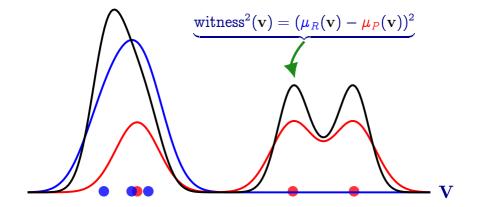




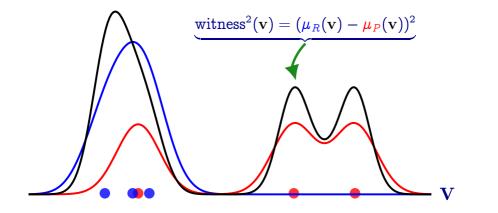
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Given J test locations $V := \{\mathbf{v}_j\}_{j=1}^J$ (V gives interpretability later),

$$extsf{UME}_V^2(P,R) = rac{1}{J}\sum_{j=1}^J extsf{witness}^2(extsf{v}_j) = U_P^2.$$

• UME_V^2 will be *D* for model comparison.

Proposition (Chwialkowski et al., 2015, Jitkrittum et al., 2016) Assume

1 Kernel k is real analytic, integrable, and characteristic;

2 V is drawn from η , a distribution with a density.

Then, for any J > 0, any P and R,

$$\mathrm{UME}_V^2(P,R)=0 \,\, \mathit{i\!f\!f}\,\, P=R$$
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 η -almost surely.

Key: Evaluating witness² is enough to detect the difference (in theory).
 Runtime complexity: O(Jn). J is small.

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Asymptotic Distribution of $\widetilde{\mathrm{UME}}_{V}^{2}(P,R) = \widehat{U}_{P}^{2}$

• Define $\psi_V(\mathbf{y}) := rac{1}{\sqrt{J}} \left(k(\mathbf{y}, \mathbf{v}_1), \dots, k(\mathbf{y}, \mathbf{v}_J) \right)^\top \in \mathbb{R}^J.$

• Let $\psi_V^P := \mathbb{E}_{\mathbf{x} \sim P}[\psi_V(\mathbf{x})] \in \mathbb{R}^J$. Let $C_V^P := \operatorname{cov}_{\mathbf{x} \sim P}[\psi_V(\mathbf{x})] \in \mathbb{R}^{J \times J}$.

Proposition (Asymptotic distribution of $\overline{U_P^2}$)

If $P \neq R$, for any V, as $n \to \infty$

$$\sqrt{n}\left[\widehat{\mathrm{UME}_V^2}(P,R)-\mathrm{UME}_V^2(P,R)
ight] \stackrel{d}{ o} \mathcal{N}(0,4\zeta_P^2),$$

where $\zeta_P^2 := (\psi_V^P - \psi_V^R)^\top (C_V^P + C_V^R)(\psi_V^P - \psi_V^R) > 0.$

Main point: When $P \neq R$, $UME_V^2(P, R)$ is asymptotically normally distributed. Simple.

But we will need the distribution of $\widehat{S}_n = \widehat{\mathrm{UME}}_V^2(P,R) - \widehat{\mathrm{UME}}_V^2(Q,R)$ which is ...?

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• Let $S := U_P^2 - U_Q^2$. So $H_0: S = 0$ and $H_1: S > 0$.

Proposition (Joint distribution of $\overline{U_P^2}$ and $\overline{U_Q^2}$

Assume that P, Q and R are all distinct. Under mild conditions, for any V,

$$1 \quad \sqrt{n} \left(\left(\begin{array}{c} \overline{U_P^2} \\ \overline{U_Q^2} \end{array} \right) - \left(\begin{array}{c} U_P^2 \\ U_Q^2 \end{array} \right) \right) \xrightarrow{d} \mathcal{N} \left(0, 4 \left(\begin{array}{c} \zeta_P^2 & \zeta_{PQ} \\ \zeta_{PQ} & \zeta_Q^2 \end{array} \right) \right) .$$

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Proposition (Joint distribution of \widehat{U}_P^2 and \widehat{U}_Q^2)

Assume that P, Q and R are all distinct. Under mild conditions, for any V,

$$1 \quad \sqrt{n} \left(\left(\begin{array}{c} \widehat{U_P^2} \\ \widehat{U_Q^2} \end{array} \right) - \left(\begin{array}{c} U_P^2 \\ U_Q^2 \end{array} \right) \right) \xrightarrow{d} \mathcal{N} \left(0, 4 \left(\begin{array}{c} \zeta_P^2 & \zeta_{PQ} \\ \zeta_{PQ} & \zeta_Q^2 \end{array} \right) \right).$$

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So, asymptotic null distribution is normal. Easy to get T_{α} .

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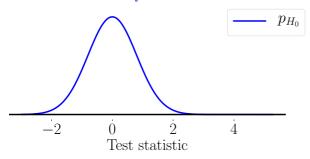
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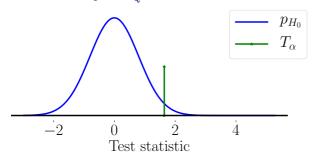
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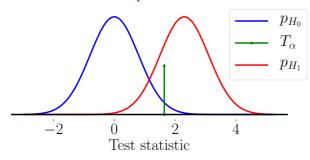
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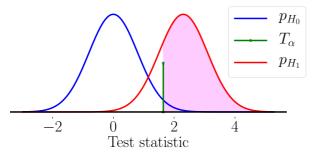
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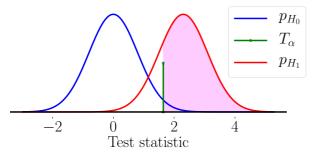
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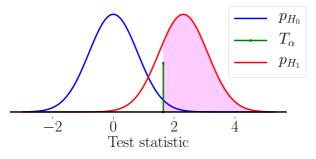
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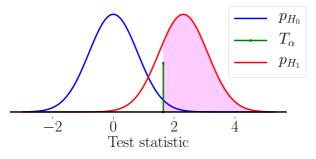


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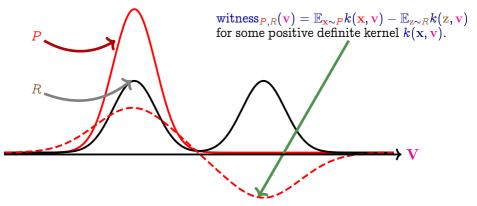
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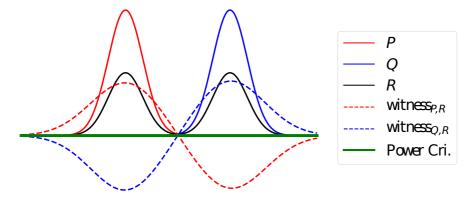
- Split the data into tr and te. Optimize V on tr. Test on te.
- Optimized V show where Q is better than P.
- For large n, $\arg \max_V power = \arg \max_V f(V)$ where $f = \frac{\operatorname{mean of } p_{H_1}}{\operatorname{std of } p_{H_1}}$. Call f the power criterion.

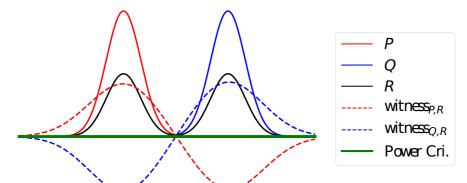
Recall the witness function between P and R:



Assume only one test location \mathbf{v} . Recall

$$\mathrm{UME}^2_\mathbf{v}(P,R) = \mathrm{witness}^2_{P,R}(\mathbf{v}) = (\mu_P(\mathbf{v}) - \mu_R(\mathbf{v}))^2$$

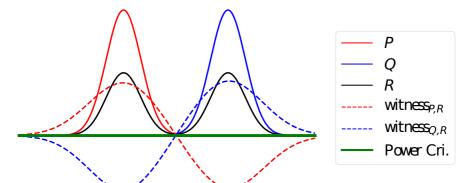




Power criterion(v) = f(v) is a function such that maximizing it corresponds to maximizing the test power.

 $f(\mathbf{v}) = rac{\mathrm{witness}_{P,R}^2(\mathbf{v}) - \mathrm{witness}_{Q,R}^2(\mathbf{v})}{\mathrm{standard\ deviation}_{P,Q,R}^2(\mathbf{v})} = rac{U_P^2 - U_Q^2}{\sqrt{4(\zeta_P^2 - 2\zeta_{PQ} + \zeta_Q^2)}}$

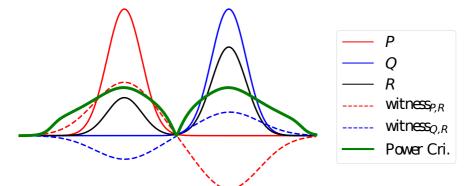
 $f(\mathbf{v}) > 0 \implies Q \text{ is better in the region around } \mathbf{v}$ $f(\mathbf{v}) < 0 \implies P \text{ is better in the region around } \mathbf{v}$



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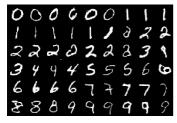
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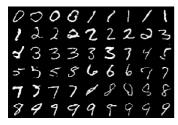
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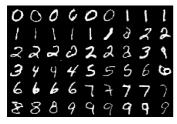
 $Q = \mathrm{LSGAN}$ [Mao et al., 2017]



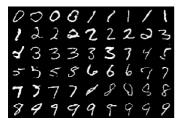
P = GAN

[Goodfellow et al., 2014]

- Set V = 40 (real) images of digit $i = 0, \dots, 9$.
- Evaluate power criterion with n = 2000.
- Q is better at "1" and "5". P is slightly better at "3". Interpretable.



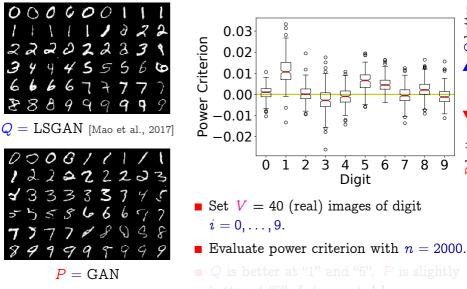
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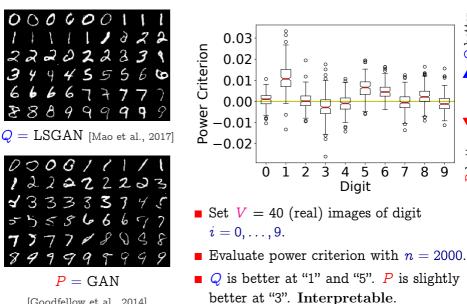
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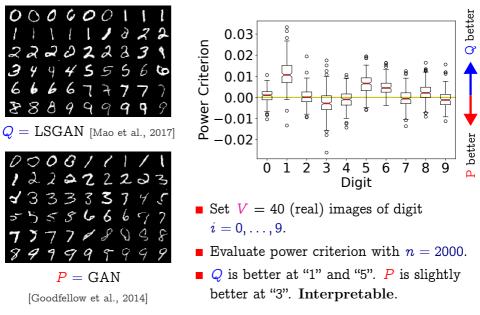


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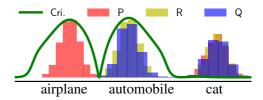
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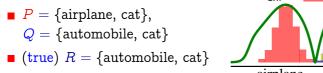


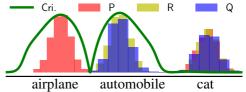
(Gaussian kernel on top of features from a CNN classifier.)

- P = {airplane, cat},
 Q = {automobile, cat}
- (true) $R = \{ \text{automobile, cat} \}$

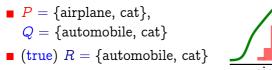


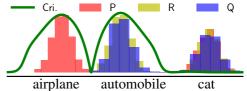
 Gaussian kernel on 2048 features extracted by the Inception-v3 network at the pool3 layer.



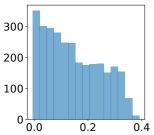


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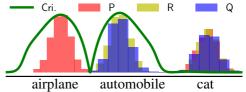
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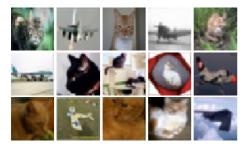
Histogram of power criterion values $f(\mathbf{v})$ evaluated at $\mathbf{v} = \{ \text{airplane, automobile, cat} \}$.

 All non-negative. ⇒ Q is equally good or better than P everywhere.

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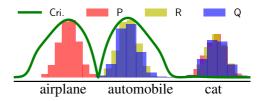


 Gaussian kernel on 2048 features extracted by the Inception-v3 network at the pool3 layer.



Images v with the lowest values of $f(v) \approx 0$. $\implies P, Q$ perform equally well in these regions.

- P = {airplane, cat},
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- (true) $R = \{$ automobile, cat $\}$



 Gaussian kernel on 2048 features extracted by the Inception-v3 network at the pool3 layer.



Images v with the highest values of f(v) > 0. $\implies Q$ is better than P in these regions.

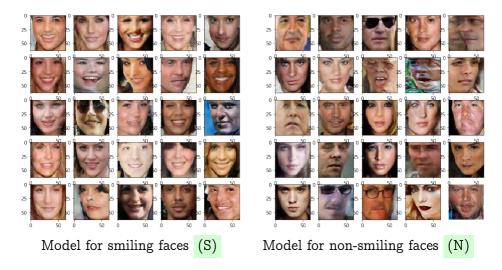


Real smiling faces (RS)



Real non-smiling faces (NS)

- Two datasets for training two models.
- Center-cropped CelebA images to 64×64 pixels.



Trained with DCGAN. Get two models.

- Report avg rejection rate (e.g., rate of claiming Q is better).
- Fréchet Inception Distance (FID) (Heusel et al., 2017). Not a test. If FID(P, R) > FID(Q, R), claim Q is better.
- $\mathbf{RS} = \mathbf{real}$ smiling images. $\mathbf{RN} = \mathbf{real}$ non-smiling images.

 $\mathbf{RM} = \text{mixture of RS and RN}$

- FID claims *Q* is better when the two models are equally good. Not account for uncertainty.
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Case	P	Q	R	Truth	Rel-U	Rel-UME		FID	FID diff.
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3.	S	Ν	RN Rej	0.57	1.0	1.0	1.0	5.25 ± 0.75
4.	S	Ν	RM Not rej	0.0	0.0	0.0	0.0	-4.55 ± 0.82

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- *r* : unknown data generating density (unknown).

• Observe $Z_n \overset{i.i.a.}{\sim} R$ and have explicit p, q.

 H_0 : p and q equally model r H_1 : q models r better.

Formulate as

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Problem: No sample from p. Cannot estimate $\mathbb{E}_{\mathbf{x} \sim p}[k_{\mathbf{v}}(\mathbf{x})]$.

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 $(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{z} \sim r}[\quad T_p k_{\mathbf{v}}(\mathbf{z}) \quad] - \mathbb{E}_{\mathbf{x} \sim p}[\quad T_p k_{\mathbf{v}}(\mathbf{x}) \quad]$

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Recall witness(**v**) = $\mathbb{E}_{\mathbf{z} \sim r}[k_{\mathbf{v}}(\mathbf{z})] - \mathbb{E}_{\mathbf{x} \sim p}[k_{\mathbf{v}}(\mathbf{x})]$ **Problem:** No sample from *p*. Cannot estimate $\mathbb{E}_{\mathbf{x} \sim p}[k_{\mathbf{v}}(\mathbf{x})]$.

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 Can construct Rel-FSSD test similarly: optimize V to show where Q is better, asymptotic normality, etc.

FSSD is a Proper Discrepancy Measure

FSSD²(p, r) =
$$\frac{1}{dJ} \sum_{j=1}^{J} ||\mathbf{g}_{p,r}(\mathbf{v}_j)||_2^2$$
 where
 $\mathbf{g}_{p,r}(\mathbf{v}) = \mathbb{E}_{\mathbf{z}\sim r} \left[\frac{1}{p(\mathbf{z})} \frac{d}{d\mathbf{z}} [k_{\mathbf{v}}(\mathbf{z}) \boldsymbol{p}(\mathbf{z})] \right]$ (Stein witness)

Theorem (FSSD is a discrepancy measure (Jitkrittum et al., 2017)) Main conditions:

- 1 (Nice kernel) Kernel k is C_0 -universal, and real analytic e.g., Gaussian kernel.
- 2 (Vanishing boundary) $\lim_{\|\mathbf{x}\| \to \infty} p(\mathbf{x}) k_{\mathrm{v}}(\mathbf{x}) = \mathbf{0}.$

3 (Avoid "blind spots") Locations $\mathbf{v}_1,\ldots,\mathbf{v}_J\sim\eta$ which has a density. Then, for any $J\geq 1$, η -almost surely,

 $\mathrm{FSSD}^2 = 0 \iff p = r.$

Summary: Evaluating the witness at random locations is sufficient to detect the discrepancy between p, r.

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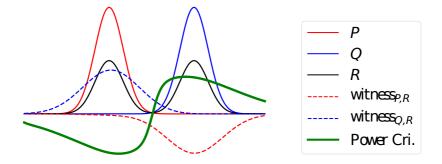
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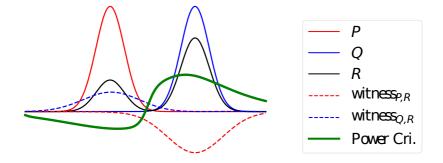
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Relative FSSD Witness Function



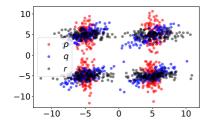
- Unlike UME which cares about probability mass, FSSD cares about shape of density functions.
- In FSSD, p, q are represented by $\nabla_x \log p(x)$ and $\nabla_y \log q(y)$ (instead of samples).

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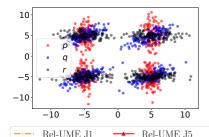
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Experiment: 2d Blobs



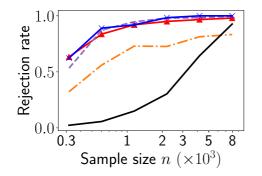
- Problem in R². Difference in small scale relative to the global structure.
- q is closer to r. So, H_1 is true.

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Rel-FSSD J1



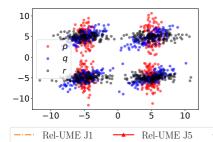
 Rel-MMD (Bounliphone et al., 2014) suffers from a wrong choice of Gaussian bandwidth.

Rel-FSSD J5

 Proposed Rel-UME, Rel-FSSD can optimize their parameters (maximizing test power).

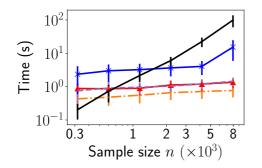
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Rel-MMD

Summary

Propose a model comparison test Relative UME :

- Statistical testing: account for randomness of the distance
- Linear-time: runtime complexity = O(n)
- Interpretable: tells where Q is better P (vice versa)

Another variant Relative FSSD : P, Q are explicit (unnormalized) density functions. No need to sample.

Informative Features for Model Comparison W. Jitkrittum, H. Kanagawa, P. Sangkloy, J. Hays, B. Schölkopf, A. Gretton NeurIPS 2018 Python code: https://github.com/wittawatj/kernel-mod



Thank you

•
$$V := {\mathbf{v}_1, \dots, \mathbf{v}_J} = J$$
 test locations
 $UME_V^2(\boldsymbol{P}, R) = \frac{1}{J} \sum_{j=1}^J (\mu_{\boldsymbol{P}}(\mathbf{v}_j) - \mu_R(\mathbf{v}_j))^2$

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 $\begin{array}{l} \text{Let } \psi_V(\mathbf{x}) := \frac{1}{\sqrt{J}} \left(k(\mathbf{x},\mathbf{v}_1),\ldots,k(\mathbf{x},\mathbf{v}_J) \right)^\top \in \mathbb{R}^J. \text{ Equivalently,} \\ \\ \text{UME}_V^2(\textbf{\textit{P}},R) = \left\| \mathbb{E}_{\mathbf{x}\sim \textbf{\textit{P}}}[\psi_V(\mathbf{x})] - \mathbb{E}_{\mathbf{z}\sim R}[\psi_V(\mathbf{z})] \right\|_2^2. \end{array}$

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 $\mathbb{UME}_V^2({m P},R) = ig\|\mathbb{E}_{\mathbf{x}\sim {m P}}[\psi_V(\mathbf{x})] - \mathbb{E}_{\mathbf{z}\sim R}[\psi_V(\mathbf{z})]ig\|_2^2.$

• Empirical $\widetilde{\text{UME}^2}(P, R)$ = replace \mathbb{E} 's above with $\frac{1}{n} \sum_{i=1}^{n}$.

Write U_P² = UME²(P, R) and U_Q² = UME²(Q, R).
Let S := U_P² - U_Q². So H₀: S = 0 and H₁: S > 0.

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Proposition (Joint distribution of $\widehat{U_P^2}$ and $\widehat{U_Q^2}$

Assume that P, Q and R are all distinct. Under mild conditions,

$$1 \quad \sqrt{n} \left(\begin{pmatrix} U_P^2 \\ \widehat{U}_Q^2 \end{pmatrix} - \begin{pmatrix} U_P^2 \\ U_Q^2 \end{pmatrix} \right) \xrightarrow{d} \mathcal{N} \left(0, 4 \begin{pmatrix} \zeta_P^2 & \zeta_{PQ} \\ \zeta_{PQ} & \zeta_Q^2 \end{pmatrix} \right);$$

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So, asymptotic null distribution is normal. Easy to get T_{α}

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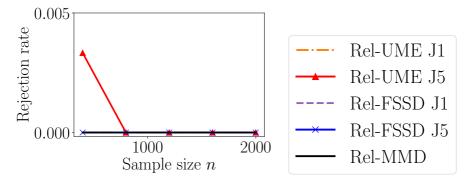
Experiment: Mean Shift

- Model 1: $p = \mathcal{N}([0.5, 0, \dots, 0], I)$. Model 2: $q = \mathcal{N}([1, 0, \dots, 0], I)$
- Data distribution $r = \mathcal{N}(0, I)$. Defined on \mathbb{R}^{50} .
- Set $\alpha = 0.05$. Should not reject H_0 .

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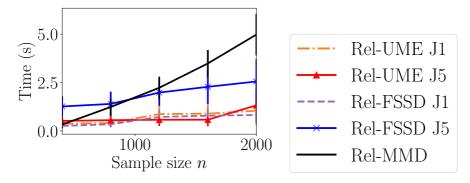
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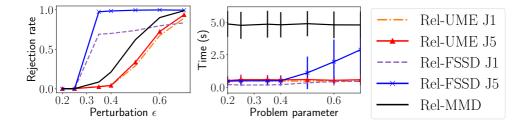
• MMD runs in $O(n^2)$ time.

Proposed Rel-UME and Rel-FSSD run in O(n).

- **p**, q, r are all RBM models. d = 20 dimensions. n = 2000.
- $\begin{array}{l} \bullet \quad g_{\mathbf{B},\mathbf{b},\mathbf{c}}(\mathbf{x}) := \frac{1}{Z} \sum_{\mathbf{h}} \exp\left(\mathbf{x}^{\top} \mathbf{B} \mathbf{h} + \mathbf{b}^{\top} \mathbf{x} + \mathbf{c}^{\top} \mathbf{h} \frac{1}{2} \|\mathbf{x}\|^2\right) \text{ where } \\ \mathbf{h} \in \{-1,1\}^5. \end{array}$
- Define $r(\mathbf{x}) := g_{\mathbf{B},\mathbf{b},\mathbf{c}}(\mathbf{x})$ for some randomly drawn $\mathbf{B},\mathbf{b},\mathbf{c}$.
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- **B**P = B but with ϵ added to its first entry $B_{1,1}$
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- Let $p(\mathbf{x}) := g_{\mathbf{B}^p, \mathbf{b}, \mathbf{c}}(\mathbf{x})$, and $q(\mathbf{x}) := g_{\mathbf{B}^q, \mathbf{b}, \mathbf{c}}(\mathbf{x})$.
- **B**^{*p*} = **B** but with ϵ added to its first entry $B_{1,1}$
- **B** q = **B** but with 0.3 added to its first entry $B_{1,1}$
- If $\epsilon > 0.3$, q is better. Should reject H_0 .



- Models and and true distribution are very close. Difficult.
- FSSD has access to the density. Higher power than UME, MMD (rely on samples).

 $\text{Recall Stein witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{y} \sim q}(T_p k_{\mathbf{v}})(\mathbf{y}) - \mathbb{E}_{\mathbf{x} \sim p}(T_p k_{\mathbf{v}})(\mathbf{x})$

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$$(T_p k_\mathbf{v})(\mathbf{x}) = rac{1}{p(\mathbf{x})} rac{d}{d\mathbf{x}} [k(\mathbf{x},\mathbf{v})p(\mathbf{x})].$$

Then, $\mathbb{E}_{\mathbf{x} \sim p}(T_p k_{\mathbf{v}})(\mathbf{x}) = 0.$

[Liu et al., 2016, Chwialkowski et al., 2016]

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 Normalizer
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 Normalizer cancels

Then, $\mathbb{E}_{\mathbf{x}\sim p}(T_p k_{\mathbf{v}})(\mathbf{x}) = 0.$

[Liu et al., 2016, Chwialkowski et al., 2016]

$$\mathbb{E}_{\mathbf{x}\sim p}\left[(T_{p}k_{\mathbf{v}})(\mathbf{x})\right] = \int_{-\infty}^{\infty} \left[\frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x})p(\mathbf{x})]\right] p(\mathbf{x}) d\mathbf{x}$$
$$= \int_{-\infty}^{\infty} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x})p(\mathbf{x})] d\mathbf{x}$$
$$= [k_{\mathbf{v}}(\mathbf{x})p(\mathbf{x})]_{\mathbf{x}=-\infty}^{\mathbf{x}=-\infty}$$
$$= 0$$

 $(ext{assume lim}_{|\mathbf{x}|
ightarrow \infty} k(\mathbf{v}, \mathbf{x}) p(\mathbf{x}))$

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